

Evaluation of Edge Assembly Crossover for Hybrid GA

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Abstract

Traveling Salesman Problem (TSP) is one of the representative combinatorial optimization problems. The promising approach to solve TSP is Genetic Algorithm (GA). GA has global search ability, and heuristic is used in order to compensate local search ability, because GA is lack of local search ability. Hybrid GA (HGA) combined with heuristics can be expected to obtain high quality solutions. We employ Lin-Kernighan heuristics which is very effective in TSP. Because crossover is one of the important operators of GA, lots of crossovers are proposed for TSP. We employ Edge Assembly Crossover (EAX) which can obtain high quality solutions. We evaluate the proposed HGA combined EAX and heuristics and show that it finds the best solutions.

Key Words:

Traveling Salesman Problem, Genetic Algorithm, Edge Assembly Crossover

1 Introduction

Traveling Salesman Problem (TSP) is a problem which finds the shortest tour to visit all the cities only once and come back to the starting city, and it is one of the representative combinatorial optimization problems. It is applied in many fields such as vehicle course plan, scheduling, X-ray crystal structure analysis, and VLSI wiring etc¹⁾²⁾.

TSP is known as an NP-complete problem. It is difficult to find the optimal solution, because the total number of combination $\frac{(N-1)!}{2}$ increases more than exponentially with increase of the number of cities N.

The promising approach to solve TSP is Genetic Algorithm (GA). In spite of having global search ability, GA lacks in local search ability. Heuristics is used in order to compensate local search ability. We employ Lin-Kernighan heuristics which is very effective in TSP. The combination of GA and heuristics is called Hybrid GA (HGA).

Because crossover is one of the important operators of GA, many crossovers have been proposed for TSP,

for example, partially matched crossover (PMX), order crossover (OX), cycle crossover (CX), maximal preservative crossover (MPX)⁷⁾, greedy subtour crossover (GSX)⁵⁾, edge recombination (ER), and edge assembly crossover (EAX). We employ EAX which is excellent in characteristic preservation, and can generate a wide variety of offspring. Nagata and Kobayashi showed good search ability of EAX by comparison experiment with the traditional crossover (EX, EXX) and the traditional local search operators³⁾. In addition, they found high quality solutions at TSPs (101-3,038cities) on the TSPLIB95 using GA that employed EAX, and they did not use any other local search heuristics⁴⁾.

We evaluate the proposed HGA combined EAX and heuristics. We perform a comparison experiment with MPX and GSX in order to evaluate the quality of a solution.

2 Genetic Algorithms

To use a GA, we must represent a solution of the problem as genotype. The GA randomly creates a population of solution(in form of chromosomes) and applies genetic operators(crossover, mutation, and selection) to generate new solutions.

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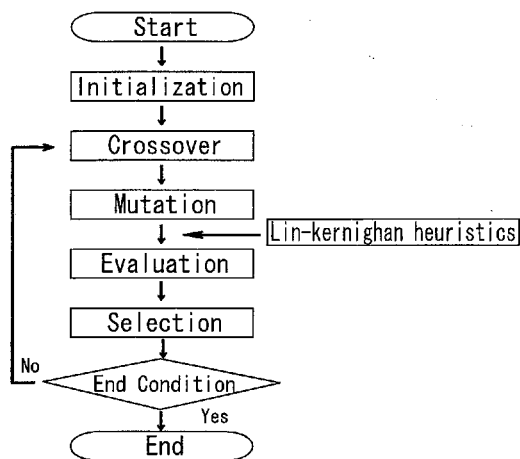


Fig. 1 The flow chart of HGA

2.1 Hybrid GA

In spite of having global search ability, GA lacks in local search ability. Employing local search heuristics (Fig.1), GA is vastly improved⁵⁾. The combination of GA and heuristics algorithm is called Hybrid GA (HGA). HGA is adopted in many cases such as a combinatorial optimization problem and real world applications⁶⁾.

2.2 A multi-community model based on GENITOR-TYPE GA

A multi-community model based on GENITOR-TYPE GA is used in this paper.

(1) A multi-community GA (Island model)

The island model is called by the analogy from population genetics. The population is divided into some subpopulation, and a part of subpopulation is exchanged (migration) at intervals of a certain generation (migration interval). The island model can maintain diversity in population.

(2) GENITOR-TYPE GA

GENITOR⁹⁾ has some characteristics.

- Using linear ranking for selecting parents.
- In each generation, crossover is performed only for one pair and mutation is performed only for one individual.

GENITOR is acknowledged hard to converge prematurely and stagnate.

2.3 Genetic Coding

Path representation that city names are enumerated in turn from the starting city is used for coding.

For example, tour (1 - 4 - 2 - 7 - 3 - 6 - 5) is expressed like Fig.2.

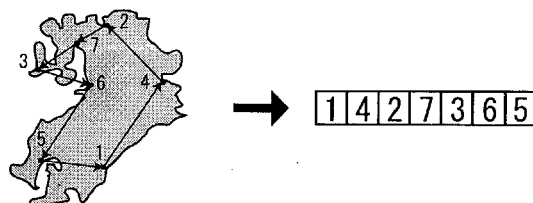


Fig. 2 Genetic Coding

2.4 Genetic Operations

(1) Mutation

To clarify the effect of crossover, mutation is not employed.

(2) Fitness Evaluation

Individual which has the smaller tour length in population is given higher fitness. Therefore, the fitness of an individual is defined as the following formula,

$$fitness = \frac{1}{D}$$

Here, D is tour length defined as follows,

$$D = \sum_{i=1}^N d_{L(i),L(i+1)}$$

N : the number of cities

d_{ij} : distance between cities i and j

$L(i)$: the city which it visits to the i -th

(3) Selection

In GA, it is determined whether an individual can survive based on the fitness. If the offspring is better than the worst parent, it is immediately inserted into population to replace the worst parent. As for a child, only one individual is generated by each generation.

(4) Crossover (EAX)

Parent's characteristics are inherited through crossover⁸⁾. In TSP, it can be said that the good character which should be inherited to offspring is the subtour which was partially successful. The EAX is excellent in characteristic preservation, because intermediate individual are made of only edges of parents. In addition, the EAX can generate a wide variety of offspring.

The intermediate individual is modified into a valid tour, because it consists of some subtour.

Step1 An intermediate individual T which consists of some subtour is set.

Step2 Subtour U_r , which consists of number of the fewest edge subtour $U_i(i = 1, 2, \dots)$ in T is chosen.

Step3 The pair $(v_1, v_2), (v_3, v_4)$ from which the value of a formula becomes the maximum is found.

$$w(v_1, v_2) + w(v_3, v_4) - w(v_1, v_4) - w(v_3, v_2) \quad (1)$$

$$((v_1, v_2) \in U_r, (v_3, v_4) \in U_i(i \neq r))$$

Step4 The subtour containing edge (v_3, v_4) is set as U_s . Edge (v_1, v_2) and (v_3, v_4) are removed, and edge (v_1, v_4) and (v_3, v_2) are added. As a result, U_r and U_s are connected.

Step5 Modification operation is ended when intermediate individual T becomes one tour. It returns to *Step1* except it.

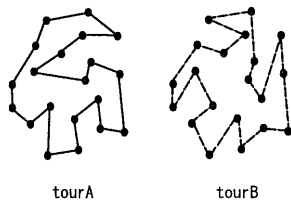


Fig. 3 An example parents (tourA, tourB)

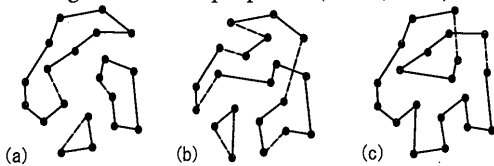


Fig. 4 Examples of intermediate individual obtained from the parents

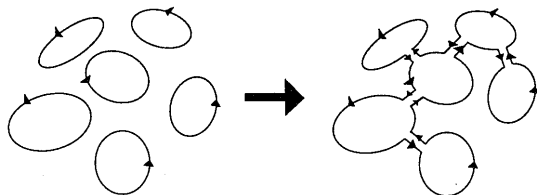


Fig. 5 An example of intermediate individuals (left) and a valid individual (right) obtained by modification

3 Comparison experiments of three crossovers

The comparison experiments with MPX and GSX are performed for evaluation of EAX.

3.1 Benchmarks and Experimental conditions

(1) Benchmarks

Ten TSPs(318-3795cities) are used on the TSPLIB95¹ which is the representative benchmark of TSP.

(2) GA parameters

- Population size ... 32
- Number of islands ... 2
- Selection bias ... 1.25
- Mutation rate ... 0.0
- Migration interval ... 500
- Number of migrants ... 3

(3) Terminal conditions

- In case an elite is not replaced for 2000 successive generations, or
- In case the generation gets at 10000.

(4) Computational environment

- CPU: Intel Pentium III (935MHz)
- Main memory: 256MB
- OS: FreeBSD 4.8
- Compiler: gcc (ver.2.95.4)

3.2 Quality of the solution

Quality of the solution is evaluated by the following formula.

$$quality(\%) = \frac{tour\ length - optimum}{optimum} \times 100 \quad (2)$$

3.3 Results and Discussions

Table1 is result of a comparison experiments of three crossovers. The experiments were performed 20 times to each problem. Fig.6 is change of tour length of the problem "pcb3038".

In case the number of cities is small i.e. 198-318, three crossovers (EAX,MPX,GSX) have scarcely differences. However, As the number of cities increases, compared with GSX, the high quality solutions found by EAX and MPX. In case the number of cities is big i.e. 3038-3795,

¹URL <http://www.iwr.uni-heidelberg.de/groups/comopt/software/TSPLIB95/>

Table 1 Result of comparison experiments of three crossovers

EAX					
Problem	Optimum	Ratio of opt.	Quality(%)	Ave. gen.	CPU time(s)
d198	15,780	20/20	0.000	2045	500.34
lin318	42,029	20/20	0.000	2100	276.61
pcb442	50,778	20/20	0.000	2100	525.49
att532	27,686	16/20	0.012	2180	593.90
rl1323	270,199	8/20	0.005	2295	674.72
fl1577	22,249	3/20	0.025	2780	3401.34
d2103	80,450	0/20	0.049	2485	1580.26
pr2392	378,032	8/20	0.003	2600	594.70
pcb3038	137,694	2/20	0.011	2770	1140.86
fl3795	28,772	11/20	0.051	2990	10344.28
GSX					
Problem	Optimum	Ratio of opt.	Quality(%)	Ave. gen.	CPU time(s)
d198	15,780	20/20	0.000	2040	22.29
lin318	42,029	20/20	0.000	2150	19.07
pcb442	50,778	17/20	0.007	2300	7.14
att532	27,686	14/20	0.018	2575	27.42
rl1323	270,199	6/20	0.017	2570	51.10
fl1577	22,249	0/20	0.103	3485	105.67
d2103	80,450	0/20	0.110	2770	50.54
pr2392	378,032	0/20	0.084	2875	25.62
pcb3038	137,694	0/20	0.098	3530	40.89
fl3795	28,772	0/20	0.306	3955	136.67
MPX					
Problem	Optimum	Ratio of opt.	Quality(%)	Ave. gen.	CPU time(s)
d198	15,780	20/20	0.000	2045	93.73
lin318	42,029	20/20	0.000	2110	31.14
pcb442	50,778	20/20	0.000	2105	31.10
att532	27,686	17/20	0.009	2505	60.77
rl1323	270,199	6/20	0.007	2390	87.15
fl1577	22,249	2/20	0.025	3055	482.97
d2103	80,450	1/20	0.026	2785	310.39
pr2392	378,032	1/20	0.008	2795	55.86
pcb3038	137,694	0/20	0.017	3280	133.79
fl3795	28,772	2/20	0.104	3755	690.39

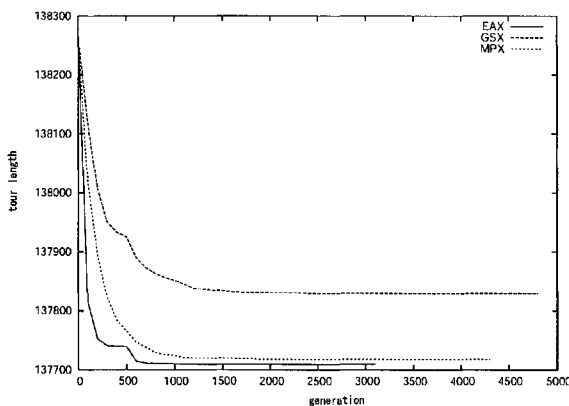


Fig. 6 Change of tour length(pcb3038)

the convergence of EAX is earlier and comparatively high quality solutions is found. It is thought that the heredity of the characteristics of EAX is excellent. EAX is understood that a calculation burden is large compared with MPX and GSX. The reason is probable that 2^k (k is number of AB-cycle) candidates of offspring are generated from two parents with EAX. Improvement to the selection method and the division method of AB-cycle is important in order to reduce execution time.

4 Conclusions

We evaluate the proposed HGA combined EAX and heuristics. We perform a comparison experiment with three crossovers (EAX, MPX, and GSX) in order to evaluate the quality of a solution. In case the number of cities is large i.e. 3038-3795, the convergence of EAX is earlier and comparatively high quality solutions is found. The excellent search ability of EAX was confirmed by a comparison experiment. But, EAX is understood that a calculation burden is large compared with MPX and GSX. We want to improve the selection method and the division method of AB-cycle in order to reduce execution time.

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Appendices

The following operations generate an intermediate individual.

A.1 Definitions

(Def. 1) Graph G_{AB}

Graph G_{AB} is defined as follows.

$$G_{AB}=(V,E_A \cup E_B)$$

E_A :an set of edges that constructs tourA

E_B :an set of edges that constructs tourB

(Def. 2) AB-cycle

AB-cycle is a closed path which consists of even edge which follows $e_A \in E_A$ and $e_B \in E_B$ by turns on G_{AB} .

(Def. 3) Exchangeable Edge Set (E-set)

E-set has the equal number of the edge belonging to $E_A \cap D$ and the equal number of the edge belonging to $E_B \cap D$ on each point on subset D of $E_A \cup E_B$.

A.2 Outline of EAX

Step1 Generate AB-cycle from G_{AB} .(Fig.8)

Step2 Generate E-set from combine of arbitrary AB-cycle.

Step3 Generate an intermediate individual by applying the E-set to tourA.(Fig.9)

Step4 Modify the intermediate individual.

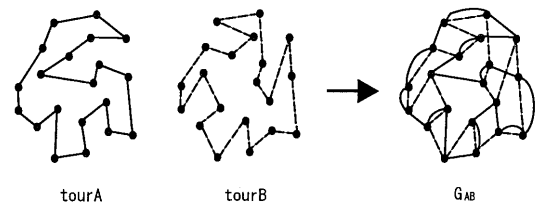


Fig. 7 Parents(tourA,tourB) and G_{AB}

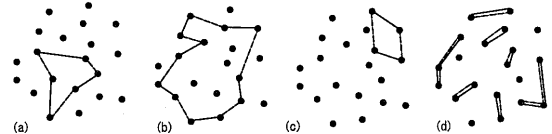


Fig. 8 An example of AB-cycles obtained from

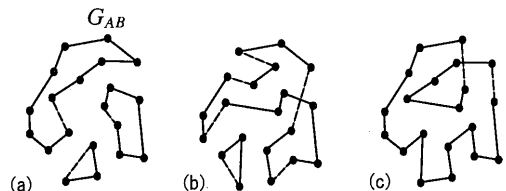


Fig. 9 Examples of intermediate individuals obtained from E-set

A.3 AB-cycle

(1) Generation of AB-cycle

A path is formed by choosing $e_A \in E_A$ and $e_B \in E_B$ at random by turns on G_{AB} . If the closed path which consists of even edge is formed, it is extracted as AB-cycle. This operation is continued until all the edge on G_{AB} is lost.

(2) Selection of AB-cycle

Total of intermediate individual which can be constituted by combining $e_A \in E_A$ with $e_B \in E_B$ correspond one-to-one to combination of AB-cycle. In other words, If k AB-cycle is generated, 2^k intermediate individual can be generated from tourA and tourB. Therefore, it is necessary to choose AB-cycle. Then, the following two selection methods are proposed.

(a) Random Selection

AB-cycle is chosen at random with probability 0.5.

(b) Heuristic Selection

Heuristic method that considers a balance between exploitation and exploration is proposed. We use $\alpha = 1$.

$$gain_i = \sum_{e \in AB\text{-cycle}_i \cap E_A} w(e) - \sum_{e \in AB\text{-cycle}_i \cap E_B} w(e)$$

$$f_{A_i} = \sum_{e \in AB\text{-cycle}_i \cap E_A} f(e), \quad f_{B_i} = \sum_{e \in AB\text{-cycle}_i \cap E_B} f(e)$$

$$\bar{f}_A = \frac{\sum_i \sum_{e \in AB\text{-cycle}_i \cap E_A} f(e)}{\sum_i n_i / 2}$$

$$\bar{f}_B = \frac{\sum_i \sum_{e \in AB\text{-cycle}_i \cap E_B} f(e)}{\sum_i n_i / 2}$$

$$div_i = (f_{A_i} - \bar{f}_A \times n_i / 2) - (f_{B_i} - \bar{f}_B \times n_i / 2)$$

$$sum_gain_plus = \sum_{i \text{ s.t. } gain_i \geq 0} gain_i$$

$$sum_div_plus = \sum_{i \text{ s.t. } div_i \geq 0} div_i$$

$$GAIN_i = \frac{gain_i}{sum_gain_plus}$$

$$DIV_i = \frac{div_i}{sum_div_plus}$$

$$F_i = GAIN_i + \alpha \times DIV_i$$

AB-cycle_i : i-th AB-cycle (i = 1, 2, ..., k)

e : an edge

w(e) : weight of e

f(e) : ratio of e in population

A.4 Exchangeable Edge Set (E-set)

The combination of arbitrary AB-cycle can constitute E-set. An intermediate individual is generated by applying E-set to tourA as follows.

$$E_A \rightarrow (E_A \cap \bar{D}) \cup (E_B \cap D)$$